

CHAPTER: ROTATIONAL MOTION

Multiple Choice Questions

1. A system of particles is called a rigid body, when

(a) any two particles of system may have displacements in opposite directions under action of a force

(b) any two particles of system may have velocities on opposite directions under action of a force

(c) any two particles of system may have a zero relative velocity

(d) any two particles of system may have displacements in same direction under action of a force

2. The centre of mass of a system of particles does not depend on

- (a) masses of the particles
- (c) position of the particles

(b) internal forces of the particles

(d) relative distance between two particles

- 3. In pure rotation, all particles of the body
- (a) move in a straight line
- (c) move in non-concentric circles
- (b) move in concentric circles(d) have same speed

4. For n particles in a space, the suitable expression for the x-coordinate of the centre of mass of a system is

(a)
$$\frac{\sum m_i x_i}{m_i}$$
 (b) $\frac{\sum m_i x_i}{M}$ (c) $\frac{\sum m_i y_i}{M}$ (d) $\frac{\sum m_i z_i}{M}$

5. Which of the following points is the likely position of the centre of mass of the system shown in figure?

| (a) | A |
|-----|---|
|-----|---|

(b) B

(c) C

(d) D

R/2 R/2 Sand

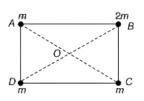
6. Two bodies of masses 1 kg and 2 kg are lying on x-y plane at (1,2) and (-1,3) respectively. What are the coordinates of centre of mass?

(a) (2, N-1) (b) $\left(\frac{8}{3}, -\frac{1}{3}\right)$ (c) $\left(-\frac{1}{3}, \frac{8}{3}\right)$ (d) None of these

7. Three identical spheres of mass *M* each are placed at the corners of an equilateral triangle of side 2m. Taking one of the corners as the origin, the position vector of the centre of mass is

(a) $\sqrt{3}(\hat{\imath} - \hat{j})$ (b) $\frac{\hat{\imath}}{\sqrt{3}} + \hat{j}$ (c) $\frac{\hat{\imath} + \hat{\jmath}}{3}$ (d) $\hat{\imath} + \frac{\hat{\jmath}}{\sqrt{3}}$

| 8. Centre of mass of the given system of particles will be at | | | | | |
|---|--------|--|--|--|--|
| (a) OD | (b) OC | | | | |
| (c) OB | (d) A0 | | | | |



9. Two particles of equal masses have velocities $V_1 = 4 \hat{\iota} m s^{-1}$ and $V_2 = 4 \hat{\iota} m s^{-1}$. First particle has an acceleration $a_1 = (2\hat{\iota} + 2\hat{\jmath}) m s^{-2}$, while the acceleration of the other particle is zero. The centre of mass of the two particles moves in a path of
(a) straight line
(b) parabola
(c) circle
(d) ellipse

10. The centre of mass of three particles of masses 1 kg, 2 kg and 3 kg is at (3, 3, 3) with reference to a fixed coordinate system. Where should a fourth particle of mass 4 kg be placed, so that the centre of mass of the system of all particles shifts to a point (1, 1, 1)? (a) (-1, -1, -1) (b) (-2, -2, -2) (c) (2, 2, 2) (d) (1, 1, 1)?

11. A ball kept in a closed box moves in the box making collisions with the walls. The box is kept on a smooth surface. The velocity of the centre of mass

(a) of the box remains constant

(b) of the box and the ball system remains constant

(c) of the ball remains constant

(d) of the ball relative to the box remains constant

12. A force **F** is applied on a single particle P as shown in the figure. Here, **r** is the position vector of the particle. The value of torque τ is

(a) F× r

(b) r× F ′

(c) r · F

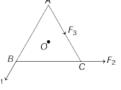
(d) $F \cdot r$

13. A force $F = 5\hat{i} + 2\hat{j} - 5\hat{k}$ acts on a particle whose position vector is $r = \hat{i} + 2\hat{j} - \hat{k}$. What is the torque about the origin?

(a) $8\hat{\imath} + 10\hat{\jmath} + 12\hat{k}$ (c) $8\hat{\imath} - 10\hat{\jmath} + 8\hat{k}$ (b) $8\hat{\imath} + 10\hat{\jmath} - 12\hat{k}$ (d) $10\hat{\imath} - 10\hat{\jmath} - \hat{k}$

14. *ABC* is an equilateral triangle with *O* as its centre. F_1 , F_2 and F_3 represent three forces acting along the sides *AB*, *BC* and *AC*, respectively. If the total torque about *O* is zero, then the magnitude of F_3 is

(a) $F_1 + F_2$ (b) $F_1 - F_2$ (c) $\frac{F_1 + F_2}{2}$ (d) 2($F_1 + F_2$)



15. The angular momentum **L** of a single particle can be represented as (a) $r \times p$ (b) $rp \sin\theta \hat{n}$ (c) $r\rho \perp \hat{n}$ (d) Both (a) and (b) (\hat{n} = unit vector perpendicular to plane of r, so that r, p and \hat{n} make right-handed system)

16. Newton's second law for rotational motion of a system of particle can be represented as (L for a system of particles)

(a) $\frac{dp}{dt} = \tau_{ext}$ (b) $\frac{dL}{dt} = \tau_{int}$ (c) $\frac{dL}{dt} = \tau_{ext}$ (d) $\frac{dL}{dt} = \tau_{int}$

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17. A particle of mass *m* moves in the *xy*-plane with a velocity *v* along the straight line AB. If the angular momentum of the particle with respect to origin O is L_A , when it is at A and L_B when it is at B, then (a) $L_A > L_B$ (b) $L_A = L_B$ (c) the relationship between L_A and L_B depends upon the slope of the line AB (d) $L_A < L_B$ 18. A point mass m is attached to a massless string whose other end is fixed at P as shown in figure. The mass is undergoing circular motion in xy-plane with centre O and constant angular speed w. If the angular momentum of the system, calculated about O and *P* be L_0 and L_P respectively, then (a) L_0 and L_P do not vary with time (b) L_0 varies with time while L_P remains constant (c) L_0 remains constant while L_P varies with time (d) L_0 and L_P both vary with time 19. A child stands at the centre of a turntable with his two arms outstretched. The turntable is set rotating with an angular speed of 40 rev min⁻¹. How much is the angular speed of the child, if he folds his hands back and thereby reduces his moment of inertia to (2/5) times the initial value? Assume that the turntable rotates without friction. (a) 40 rpm (b) 45 rpm (c) 55 rpm (d) 100 rpm 20. If the torque of the rotational motion will be zero, then the constant quantity will be (a) angular momentum (b) linear momentum (c) angular acceleration (d) centripetal acceleration 21. A particle of mass *m* is moving in yz –plane with a uniform velocity *v* with its trajectory running parallel to +ve *y*-axis and intersecting *z*-axis at z = a in figure. The change in its angular momentum about the origin as it bounces elastically from a wall at y = constant is (a) $mva \hat{e}_x$ (b) 2 mva \hat{e}_x (c) $ymv \hat{e}_x$ (d) 2 ymv \hat{e}_x 22. The variation of angular position θ of a point on a rotating rigid body with time t is shown in figure. In which direction, the body is rotating? (a) Clockwise (b) Anti-clockwise (c) May be clockwise or anti-clockwise (d) None of the above 23. A rigid body is said to be in partial equilibrium only, if (a) it is in rotational equilibrium (b) it is in translational equilibrium (c) Either (a) or (b) (d) None of the above

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| • | uilibrium? (Given, $M_1 = -$ | - | boy <i>B</i> from right edge to keep |
|--|-------------------------------------|---|--------------------------------------|
| (a) $\frac{4}{3}$ m | | | Ô Ô. |
| (b) 1m | | | $M_1 M_2$ |
| (c) $\frac{2}{3}$ m | | | |
| (d) Zero | | | |
| (u) Lero | | | ← 2 m → 2 m → |
| 25. The centre of g | gravity of a homogeneou | is body is the point at v | which the whole |
| | body is assumed to be co | | |
| | face of the body is assur | | i |
| (c) weight of the t (d) All of the abov | oody is assumed to be co | oncentrated | |
| (u) All of the abov | e e | | |
| 26. One solid sphe | ere A and another hollow | v sphere <i>B</i> are of same | mass and same outer radius. |
| Their moments of | inertia about their diam | neters are $I_{\rm A}$ and $I_{\rm B}$ resp | pectively, such that |
| (a) $I_{\rm A} = I_{\rm B}$ | (b) $I_{\rm A} > I_{\rm B}$ | (c) $I_{\rm A} < I_{\rm B}$ | (d) None of these |
| 27. A disc of mass | M and radius R is rotati | ng about one of its dia | meters. The value of radius of |
| gyration for the di | | | |
| (a) R/4 | (b) R/2 | | |
| (c) R/ 6 | (d) None of these | | |
| 28. A rod is rotati | ng about an axis passing | through its centre and | l perpendicular to its length. |
| The radius of gyra | | through its centre and | |
| (a) L/12 | | | Ŷ |
| (b) L / √12 | | | |
| (c) L / 6 | | | |
| (d) L / √6 | | | |
| 29 A wheel is rot: | ating at 900 rpm about it | ts avis. When the nowe | er is cut-off, it comes to rest in 1 |
| | retardation (in rad s $^{-2}$) i | | |
| (a) $-\frac{\pi}{2}$ | (b) $\frac{\pi}{4}$ | (c) $\frac{\pi}{6}$ | (d) $\frac{\pi}{2}$ |
| - | from rest and covers an | 0 | 2 |
| | ular acceleration will be | - | |
| (a) 1.2 rad s -2 | | (c) 2 rad s ⁻² | (d) 2.5 rad s ⁻² |
| | | | |
| | g fan is switched OFF, its | | |
| angular retardation | - | it make before coming | to rest? (Assume uniform |
| (a) 36 | (b) 24 | (c) 18 | (d) 12 |
| (a) 50 | (0) 2 1 | (0) 10 | (u) 12 |
| 32. A disc is rotati | ng with angular velocity | ω . A force F acts at a p | point whose position vector |
| with respect to th | e axis of rotation is <i>r</i> . Th | e power associated wi | th torque due to the force is |
| 1 | | | |
| given by | (b) (r× F)× ω | | |

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| • | vrapped around it and | it is pulled with a force | of 10N, then its angular velocity | |
|---|--|---|--|----------|
| after 4 s will be (a) 10 rads ⁻¹ | (b) 5 rads ⁻¹ | (c) 20 rads ⁻¹ | (d) None of these | |
| 34. Two discs havi | ng mass ratio $(1/2)$ as | nd diameter ratio (2/1), | then find ratio of moment of | |
| inertia. | C (1) | | | |
| (a) 2 : 1 | (b) 1:1 | (c) 1 : 2 | (d) 2 : 3 | |
| = | d keeping its mass san | | ree space. The radius of the ng physical quantities would | |
| (a) Rotational kind | - | o) Moment of inertia | | |
| (c) Angular veloci | | d) Angular momentum | | |
| | - | | | |
| angular velocity o mass 27 kg movin | f 3 rad s -1. Kinetic ene g with a velocity <i>v</i> . Th | rgy of this rotating body e value of <i>v</i> is | equal to 3 kg-m ² is rotating with v is same as that of a body of | |
| (a) 1 ms ⁻¹ | (b) 0.5 ms ⁻¹ | (c) 2 ms ⁻¹ | (d) 1.5 ms ⁻¹ | |
| | | (c) $\frac{\omega_o R}{2}$ nertia <i>I</i> and 2 <i>I</i> respectiv qual, their angular mom | (d) $2\omega_o R$ ely about their axis of rotation. enta will be in the ratio | |
| (a) 1 : 2 | | (c)2 1: | · | |
| 39. By keeping momentum of bod(a) remains constant(c) doubles | y | nes half | le the time period, then angular | |
| 40 If frigtional for | no is neglected and six | l bends her hand, then (| initially give in | |
| rotating on chair) | ce is neglected and gi | i benus ner nanu, uten (| | ··· |
| (a) I_{girl} will reduce | e | | | 4 |
| (b) <i>I</i> girl will increa | | | | 1 |
| (c) ω_{girl} will reduc | | | | <u> </u> |
| (d) None of the ab | ove | | | - |
| angular speed ω . A | A person of mass <i>M</i> is | standing on it. At one in | and mass <i>M</i> , is revolving with stant, the person jumps off the the round). The speed of the | |
| round, radially aw round of afterware | ds is | | | |

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| 42. A wheel of radius R rolls on the ground with a uniform velocity v . The velocity of topmost point relative to the bottommost point is | |
|--|-----|
| (a) v (b) 2v (c) v /2 (d) zero | |
| 43. A hoop of radius 2 m weighs 100 kg. It rolls along a horizontal floor, so that its centre of mass has a speed of 20 cms -1. How much work has to be done to stop it?(a) 10 J(b) 12 J(c) 4 J(d) 3 J | |
| 44. A drum of radius R and mass M rolls down without slipping along an inclined plane of angle θ. The frictional force (a) converts translational energy into rotational energy (b) dissipates energy as heat (c) decreases the rotational motion (d) decreases the rotational and translational motion 45. The centre of mass lie outside the body of a | |
| (a) pencil (b) shotput (c) dice (d) bangle | |
| 46. Figure shows a composite system of two uniform rods of lengths as indicated. Then the coordinates of the centre of mass of the system of rods are | ⊨→x |
| (a) moment of inertia (b) angular momentum | |
| (c) gyration (d) None of the above | |
| 48. The angular acceleration of a flywheel of mass 5 kg and radius of gyration 0.5 m is, if a torque of 10N-m is applied on it. | |
| (a) 2 rad s ⁻² (b) 4 rad s ⁻² (c) 8 rad s ⁻² (d) zero | |
| 49. When a disc rotates with uniform angular velocity, which of the following statements is incorrect. (a) The sense of rotation remains same. (b) The orientation of the axis of rotation remains same. (c) The speed of rotation is non-zero and remains same. (d) The angular acceleration is non-zero and remains same. | |
| 50. A bicycle wheel rolls without slipping on a horizontal floor. Which one of the following statements is true about the motion of points on the rim of the wheel, relative to the axis at the wheel's centre? (a) Points near the top move faster than points near the bottom. (b) Points near the bottom move faster than points near the top. (c) All points on the rim move with the same speed. |)́→ |
| | |

(d) All points have the velocity vectors that are pointing in the radial direction towards the centre of the wheel.

51. If radius of earth is reduced to half without changing its mass, then match the following columns and choose the correct option from the codes given below.

| | | | | | | | Column I | | Column II |
|----------------|--------|--------|----------------|--------|--------|----|--|----|------------------------------|
| | | | | | | А. | Angular momentum of earth | p. | Will become one fourth |
| Codes A | В | С | А | В | C | В. | Time period of rotation of earth | q. | Will become four times |
| (a) p (c) r | q p | r q | (b) p (d) p | q r | p p | С. | Rotational kinetic energy of earth | r. | No change |

52. A rigid body is rolling without slipping on the horizontal surface, then match the Column I with Column II and choose the correct option from the codes given below.

| | | | Column I Column II | |
|---------|---|---|---|--|
| | | | A. Velocity at p. $v\sqrt{2}$ point <i>A</i> , i.e. v_A | |
| Codes | - | _ | B. Velocity at q. zero point B , i.e. v_B | |
| A B | С | D | C. Velocity at r. v | |
| (a) q p | | | point C , i.e. v_C | |
| (b) p r | S | q | D. Velocity at s. 2v | |
| (c) s r | q | р | point D , i.e. v_D | |
| (d) q r | S | р | | |

Assertion-Reasoning MCOs

For question numbers 53 to 64, two statements are given-one labeled Assertion (A) and the other labelled Reason (R). Select the correct answer to these questions from the codes (a), (b), (c) and (d) are as given below

- (a) Both A and R are true and R is the correct explanation of A.
- (b) Both A and R are true but R is not the correct explanation of A.
- (c) A is true but R is false.

(d) A is false and R is also false.

53. **Assertion** The motion of the centre of mass describes the translational part of the motion. Reason Translational motion always means straight line motion.

54. Assertion The centre of mass of a body must lie on the body. **Reason** The centre of mass of a body does not lie at the geometric centre of body.

55. Assertion Two identical spherical spheres are half filled with two liquids of densities ρ_1 and ρ_2 (> ρ_1). The centre of mass of both the spheres lie at same level.

Reason The centre of mass does not lie at centre of the sphere.

56. Assertion If a particle moves with a constant velocity, then angular momentum of this particle about any point remains constant.

mmill

himmin

Reason Angular momentum does not have the units of Planck's constant.

57. Assertion When a particle is moving in a straight line with a uniform velocity, its angular momentum is constant.

Reason The angular momentum is non-zero, when particle moves with a uniform velocity.

58. Assertion For a system of particles under central force field, the total angular momentum is conserved.

Reason The torque acting on such a system is zero.

59. Assertion Inertia and moment of inertia are not same quantities. Reason Inertia represents the capacity of a body that does not oppose its state of motion or rest.

60. Assertion Moment of inertia of a particle is different whatever be the axis of rotation. **Reason** Moment of inertia does not depends on mass and distance of the particle from the axis of rotation.

61. Assertion The angular velocity of a rigid body in motion is defined for the whole body. **Reason** All points on a rigid body performing pure rotational motion are having same angular velocity.

62. Assertion If bodies slide down an inclined plane without rolling, then all bodies reach the bottom simultaneously is not necessary.

Reason Acceleration of all bodies are equal and independent of the shape.

63. Assertion A solid sphere cannot roll without slipping on smooth horizontal surface. **Reason** If the sphere is left free on smooth inclined surface, it can roll without slipping.

64. Assertion The work done against force of friction in the case of a disc rolling without slipping down an inclined plane is zero.

Reason When the disc rolls without slipping, friction is required because for rolling condition velocity of point of contact is zero

Case Based MCOs

Direction Answer the questions from 65-69 on the following case.

Centre of Mass:

The centre of mass of a body or a system of bodies is the point which moves as though all of the mass were concentrated there and all external forces were applied to it. Hence, a point at which the entire mass of the body or system of bodies is supposed to be concentrated is known as the centre of mass.

If a system consists of more than one particles (or bodies) and net external force on the system in a particular direction is zero with centre of mass at rest. Then, the centre of mass will not move along that direction. Even though some particles of the system may move along that direction.

65. The centre of mass of a system of two particles divides, the distance between them

- (a) in inverse ratio of square of masses of particles
- (b) in direct ratio of square of masses of particles
- (c) in inverse ratio of masses of particles
- (d) in direct ratio of masses of particles

66. Two bodies of masses 1 kg and 2 kg is lying in xy-plane at (-1,2) and (2,4), respectively. What are the coordinates of the centre of mass?

| (a) (1 | $\left(,\frac{10}{3}\right)$ | (b) (1,0) | (c) (0,1) |
|--------|------------------------------|-----------|-----------|
| | | | |

(d) None of these

67. Two balls of same masses start moving towards each other due to gravitational attraction, if the initial distance between them is l. Then, they meet at

| (a) $\frac{l}{2}$ | (b) <i>l</i> |
|-------------------|-------------------|
| (c) $\frac{l}{3}$ | (d) $\frac{l}{4}$ |

68. All the particles of a body are situated at a distance *R* from the origin. The distance of centre of mass of the body from the origin is

| (a) = R | $(b) \leq R$ | (c) > R | $(d) \ge d$ |
|---------|--------------|---------|-------------|
| | | | |

69. Two particles A and B initially at rest move towards each other under a mutual force of attraction. At the instant, when the speed of *A* is *v* and the speed of *B* is 2*v*, the speed of centre of mass of the system is (d) 3v

(a) zero (b) v (c) 15. v

Direction Answer the questions from 70-74 on the following case.

Torque and Centre of Gravity:

Torque is also known as moment of force or couple. When a force acts on a particle, the particle does not merely move in the direction of the force but it also turns about some point. So, we can define the torque for a particle about a point as the vector product of position vector of the point where the force acts and with the force itself. In the given figure, balancing of a cardboard on the tip of a pencil is done. The point of support, G is the centre of gravity.

70. If the **F** net, ext is zero on the cardboard, it means (b) $m_1 g = M g$ (d) $R = m_1 / g$ (a) R = Mg(c) $m_2 g = Mg$ 71. Choose the correct option. (a) τ_{Mg} about CG = 0(b) τ_R about CG = 0(c) Net τ due to $m_1 g$, $m_2 g$, ..., $m_n g$ about CG = 0(d) All of the above 72. The centre of gravity and the centre of mass of a body coincide, when (a) *g* is negligible (b) *g* is variable (c) g is constant (d) g is zero 73. If value of g varies, the centre of gravity and the centre of mass will (b) not coincide (a) coincide (c) become same physical quantities (d) None of the above 74. A body lying in a gravitational field is in stable equilibrium, if (a) vertical line through CG passes from top

(b) horizontal line through CG passes from top

(c) vertical line through CG passes from base

(d) horizontal line through CG passes from base

Direction Answer the questions from **75-79** on the following case.

Moment of Inertia:

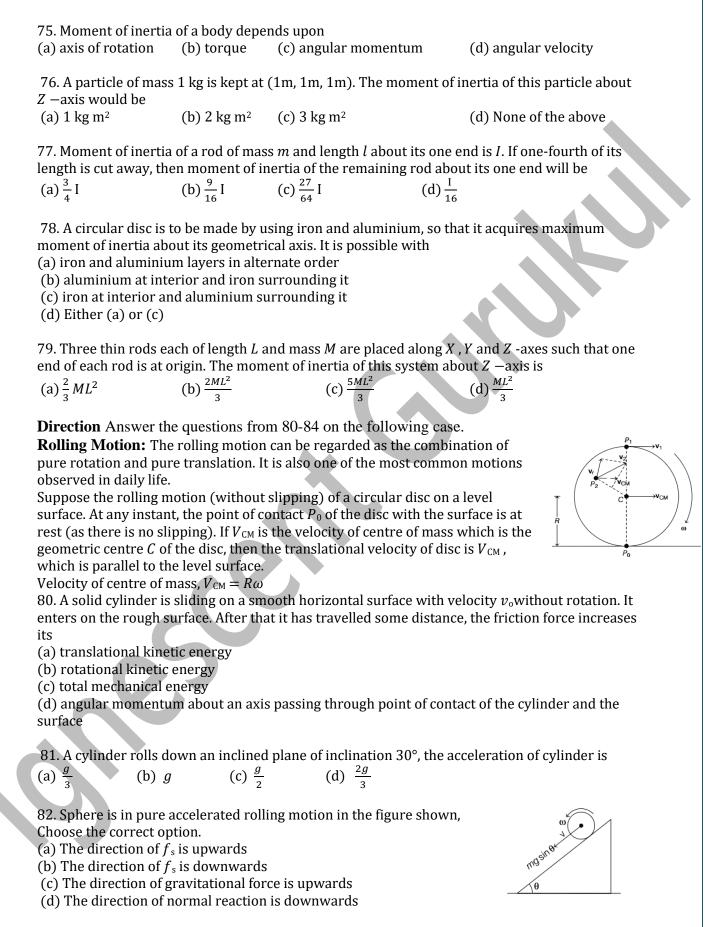
A heavy wheel called flywheel is attached to the shaft of steam engine, automobile engine etc., because of its large moment of inertia, the flywheel opposes the sudden increase or decrease of the speed of the vehicle. It allows a gradual change in the speed and prevents jerky motion and hence ensure smooth ride of passengers.

Location: Gariahat, Kolkata www.ignescentgurukul.com

 m_1g

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83. Kinetic energy of a rolling body will be

(a) $\frac{1}{2}mv_{CM}^2 (1 + k^2/R^2)$ (b) $\frac{1}{2}/\omega^2$ (c) $\frac{1}{2}mv_{CM}^2$ above

(d) None of the

84. A body is rolling down an inclined plane. Its translational and rotational kinetic energies are equal. The body is a (b) hollow sphere (c) solid cylinder (a) solid sphere (d) hollow cylinder



Multiple Choice Questions

01. (c) 02. (b) 03. (b) 04. (b) 05. (c) 06. (c) 07. (d) 08. (c) 09. (a) 10. (b) 11. (b) 12. (b) 13. (a) 14. (a) 15. (d) 16. (c) 17. (b) 18. (c) 19. (d) 20. (a) 21. (b) 22. (b) 23. (c) 24. (c) 25. (c) 26. (c) 27. (b) 28. (b) 29. (a) 30. (a) 31. (d) 32. (a) 33. (c) 34. (a) 35. (d) 36. (a) 37. (b) 38. (d) 39. (b) 40. (a) 41. (a) 42. (b) 43. (c) 44. (a) 45. (d) 46. (c) 47. (a) 48. (c) 49. (d) 50. (a) 51. (c) 52. (a) **Assertion-Reasoning MCQs** 53. (c) 54. (d) 55. (c) 56. (c) 57. (b) 58. (a) 59. (c) 60. (c) 61. (b) 62. (c) 63. (d) 64. (a) **Case Based MCQs** 65. (c) 66. (a) 67. (a) 68. (b) 69. (a) 70. (a) 71. (d) 72. (c) 73. (b) 74. (c) 75. (a) 76. (b)

77. (c) 78. (b) 79. (a) 80. (b) 81. (a) 82. (a) 83. (a) 84. (d)